

# CVXPY x NASA Course 2024

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## Homework Review

## Homework

1. work on Problems 1 - 5 from the notebook (<https://marimo.app/1/3s4nd6>)
2. analyze the following expressions as either DCP-compatible or not. Check your work with <https://dcp.stanford.edu/analyzer>
  - 2.1  $\text{sqrt}(1 + 4 * \text{square}(x) + 16 * \text{square}(y))$
  - 2.2  $\text{min}(x, \text{log}(y)) - \text{max}(y, z)$
  - 2.3  $\text{log}(\text{exp}(2 * x + 3) + \text{exp}(4 * y + 5))$
3. play the DCP quiz at <https://dcp.stanford.edu/quiz>
4. bonus problem 1: figure out how to write the non-DCP functions from q2 as DCP.
5. bonus problem 2:

*Fuel use as function of distance and speed.* A vehicle uses fuel at a rate  $f(s)$ , which is a function of the vehicle speed  $s$ . We assume that  $f : \mathbf{R} \rightarrow \mathbf{R}$  is a positive increasing convex function, with  $\text{dom } f = \mathbf{R}_+$ . The physical units of  $s$  are m/s (meters per second), and the physical units of  $f(s)$  are kg/s (kilograms per second). Let  $g(d, t)$  be the total fuel used (in kg) when the vehicle moves a distance  $d \geq 0$  (in meters) in time  $t > 0$  (in seconds) at a constant speed. Write  $g$  in DCP form. *Hint:* Check out the “perspective” atom.

## Q1 Solutions

Solution: DCP analysis

<https://marimo.app/l/bi9huq>

## Q4 and Q5 Solutions

To the board!

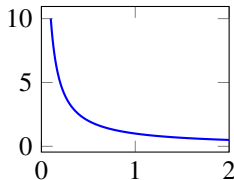
Key ideas from last time

## Convex functions

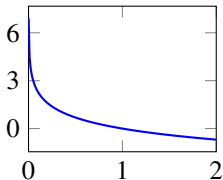
$f$  is **convex** if for  $\theta \in [0, 1]$ ,

$$f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$$

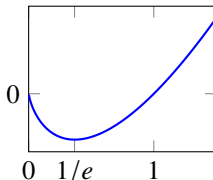
*i.e.*,  $f$  have nonnegative (upward) curvature



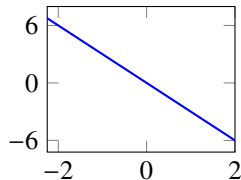
$$f(x) = 1/x$$



$$f(x) = -\log x$$



$$f(x) = x \log x$$



$$f(x) = -3x$$

## Examples on $\mathbf{R}$

convex functions:

- ▶ affine:  $ax + b$  on  $\mathbf{R}$ , for any  $a, b \in \mathbf{R}$
- ▶ exponential:  $e^{ax}$ , for any  $a \in \mathbf{R}$
- ▶ powers:  $x^\alpha$  on  $\mathbf{R}_{++}$ , for  $\alpha \geq 1$  or  $\alpha \leq 0$
- ▶ powers of absolute value:  $|x|^p$  on  $\mathbf{R}$ , for  $p \geq 1$
- ▶ positive part (relu):  $\max\{0, x\}$

concave functions:

- ▶ affine:  $ax + b$  on  $\mathbf{R}$ , for any  $a, b \in \mathbf{R}$
- ▶ powers:  $x^\alpha$  on  $\mathbf{R}_{++}$ , for  $0 \leq \alpha \leq 1$
- ▶ logarithm:  $\log x$  on  $\mathbf{R}_{++}$
- ▶ entropy:  $-x \log x$  on  $\mathbf{R}_{++}$
- ▶ negative part:  $\min\{0, x\}$



## Examples on $\mathbf{R}^n$

convex functions:

- ▶ affine functions:  $f(x) = a^T x + b$
- ▶ any norm, e.g., the  $\ell_p$  norms
  - $\|x\|_p = (|x_1|^p + \dots + |x_n|^p)^{1/p}$  for  $p \geq 1$
  - $\|x\|_\infty = \max\{|x_1|, \dots, |x_n|\}$
- ▶ sum of squares:  $\|x\|_2^2 = x_1^2 + \dots + x_n^2$
- ▶ max function:  $\max(x) = \max\{x_1, x_2, \dots, x_n\}$
- ▶ softmax or log-sum-exp function:  $\log(\exp x_1 + \dots + \exp x_n)$

## One Rule to Rule Them All

$h(f_1(x), \dots, f_k(x))$  is convex when  $h$  is convex and for each  $i$

- ▶  $h$  is increasing in argument  $i$ , and  $f_i$  is convex, or
- ▶  $h$  is decreasing in argument  $i$ , and  $f_i$  is concave, or
- ▶  $f_i$  is affine

There's a similar rule for concave compositions  
(just swap convex and concave above).

## DCP Problems

# Convex optimization

convex optimization problem:

$$\begin{array}{ll}\text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & Ax = b\end{array}$$

- ▶ variable  $x \in \mathbf{R}^n$
- ▶ equality constraints are linear
- ▶  $f_i$  are **convex**

## Linear program (LP)

$$\begin{array}{ll}\text{minimize} & c^T x + d \\ \text{subject to} & Gx \leq h \\ & Ax = b\end{array}$$

- ▶ convex problem with affine objective and constraint functions
- ▶ feasible set is a polyhedron

## Quadratic program (QP)

$$\begin{array}{ll}\text{minimize} & (1/2)x^T Px + q^T x + r \\ \text{subject to} & Gx \leq h \\ & Ax = b\end{array}$$

- ▶  $P \in \mathbf{S}_+^n$ , so objective is convex quadratic
- ▶ minimize a convex quadratic function over a polyhedron

## Second-order cone programming

$$\begin{array}{ll}\text{minimize} & f^T x \\ \text{subject to} & \|A_i x + b_i\|_2 \leq c_i^T x + d_i, \quad i = 1, \dots, m \\ & Fx = g\end{array}$$

$$(A_i \in \mathbf{R}^{n_i \times n}, F \in \mathbf{R}^{p \times n})$$

- ▶ inequalities are called second-order cone (SOC) constraints:

$$(A_i x + b_i, c_i^T x + d_i) \in \text{second-order cone in } \mathbf{R}^{n_i+1}$$

- ▶ for  $n_i = 0$ , reduces to an LP
- ▶ more general LP, QP

## Disciplined convex program

- ▶ specify objective as
  - minimize {scalar convex expression}, or
  - maximize {scalar concave expression}
- ▶ specify constraints as
  - {convex expression}  $\leq$  {concave expression} or
  - {concave expression}  $\geq$  {convex expression} or
  - {affine expression}  $=$  {affine expression}
- ▶ curvature of expressions are DCP certified, *i.e.*, follow composition rule
- ▶ DCP-compliant problems can be automatically transformed to standard forms, then solved



## CVXPY example

math:

$$\begin{array}{ll}\text{minimize} & \|x\|_1 \\ \text{subject to} & Ax = b \\ & \|x\|_\infty \leq 1\end{array}$$

- ▶  $x$  is the variable
- ▶  $A, b$  are given

CVXPY code:

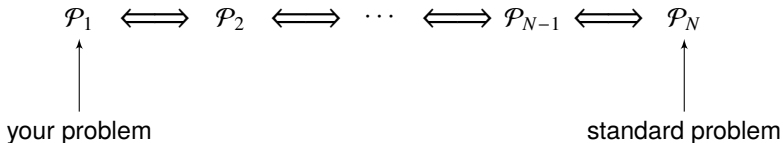
```
import cvxpy as cp

A, b = ...

x = cp.Variable(n)
obj = cp.norm(x, 1)
constr = [
    A @ x == b,
    cp.norm(x, 'inf') <= 1,
]
prob = cp.Problem(cp.Minimize(obj), constr)
prob.solve()
```

## How CVXPY works

- ▶ starts with your optimization problem  $\mathcal{P}_1$
- ▶ finds a sequence of equivalent problems  $\mathcal{P}_2, \dots, \mathcal{P}_N$
- ▶ final problem  $\mathcal{P}_N$  matches a standard form (e.g., LP, QP, SOCP, or SDP)
- ▶ calls a specialized solver on  $\mathcal{P}_N$
- ▶ retrieves solution of original problem by reversing the transformations



## Exercise: Write a CVXPY program

Try and write a program that solves

$$\begin{array}{ll}\text{minimize} & \|x - \mathbf{1}\|_2^2 \\ \text{subject to} & \|x\|_1 \leq 1\end{array}$$

Hint: you will need `sum_squares` and `norm(·, 1)`

# Outline

Transforming problems

## Change of variables

- ▶  $\phi : \mathbf{R}^n \rightarrow \mathbf{R}^n$  is one-to-one and the optimum is a possible output of  $\phi$
- ▶ consider (possibly non-convex) problem

$$\begin{array}{ll}\text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & h_i(x) = 0, \quad i = 1, \dots, p\end{array}$$

- ▶ change variables to  $z$  with  $x = \phi(z)$
- ▶ can solve equivalent problem

$$\begin{array}{ll}\text{minimize} & \tilde{f}_0(z) \\ \text{subject to} & \tilde{f}_i(z) \leq 0, \quad i = 1, \dots, m \\ & \tilde{h}_i(z) = 0, \quad i = 1, \dots, p\end{array}$$

where  $\tilde{f}_i(z) = f_i(\phi(z))$  and  $\tilde{h}_i(z) = h_i(\phi(z))$

- ▶ recover original optimal point as  $x^\star = \phi(z^\star)$

## Example

- ▶ **non-convex** problem

$$\begin{array}{ll}\text{minimize} & x_1/x_2 + x_3/x_1 \\ \text{subject to} & x_2/x_3 + x_1 \leq 1\end{array}$$

with implicit constraint  $x > 0$

- ▶ change variables using  $x = \phi(z) = \exp z$  to get

$$\begin{array}{ll}\text{minimize} & \exp(z_1 - z_2) + \exp(z_3 - z_1) \\ \text{subject to} & \exp(z_2 - z_3) + \exp(z_1) \leq 1\end{array}$$

which is **convex**

## Transformation of objective and constraint functions

suppose

- ▶  $\phi_0$  is monotone increasing
- ▶  $\psi_i(u) \leq 0$  if and only if  $u \leq 0$ ,  $i = 1, \dots, m$
- ▶  $\varphi_i(u) = 0$  if and only if  $u = 0$ ,  $i = 1, \dots, p$

standard form optimization problem is equivalent to

$$\begin{array}{ll}\text{minimize} & \phi_0(f_0(x)) \\ \text{subject to} & \psi_i(f_i(x)) \leq 0, \quad i = 1, \dots, m \\ & \varphi_i(h_i(x)) = 0, \quad i = 1, \dots, p\end{array}$$

example: minimizing  $\|Ax - b\|$  is equivalent to minimizing  $\|Ax - b\|^2$

## Converting maximization to minimization

- ▶ suppose  $\phi_0$  is monotone decreasing
- ▶ the maximization problem

$$\begin{array}{ll}\text{maximize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & h_i(x) = 0, \quad i = 1, \dots, p\end{array}$$

is equivalent to the minimization problem

$$\begin{array}{ll}\text{minimize} & \phi_0(f_0(x)) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & h_i(x) = 0, \quad i = 1, \dots, p\end{array}$$

### ▶ examples:

- $\phi_0(u) = -u$  transforms maximizing a concave function to minimizing a convex function
- $\phi_0(u) = 1/u$  transforms maximizing a concave positive function to minimizing a convex function



## Eliminating equality constraints

$$\begin{array}{ll}\text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & Ax = b\end{array}$$

is equivalent to

$$\begin{array}{ll}\text{minimize (over } z) & f_0(Fz + x_0) \\ \text{subject to} & f_i(Fz + x_0) \leq 0, \quad i = 1, \dots, m\end{array}$$

where  $F$  and  $x_0$  are such that  $Ax = b \iff x = Fz + x_0$  for some  $z$

## Introducing equality constraints

$$\begin{array}{ll}\text{minimize} & f_0(A_0x + b_0) \\ \text{subject to} & f_i(A_ix + b_i) \leq 0, \quad i = 1, \dots, m\end{array}$$

is equivalent to

$$\begin{array}{ll}\text{minimize (over } x, y_i) & f_0(y_0) \\ \text{subject to} & f_i(y_i) \leq 0, \quad i = 1, \dots, m \\ & y_i = A_ix + b_i, \quad i = 0, 1, \dots, m\end{array}$$

## Introducing slack variables for linear inequalities

$$\begin{array}{ll}\text{minimize} & f_0(x) \\ \text{subject to} & a_i^T x \leq b_i, \quad i = 1, \dots, m\end{array}$$

is equivalent to

$$\begin{array}{ll}\text{minimize (over } x, s) & f_0(x) \\ \text{subject to} & a_i^T x + s_i = b_i, \quad i = 1, \dots, m \\ & s_i \geq 0, \quad i = 1, \dots, m\end{array}$$

## Epigraph form

standard form convex problem is equivalent to

$$\begin{array}{ll}\text{minimize (over } x, t) & t \\ \text{subject to} & f_0(x) - t \leq 0 \\ & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & Ax = b\end{array}$$

## Exercise and Homework

## Q1: Portfolio Optimization

In this problem, we are going to discuss how to use a model of a market to maximize profit. Portfolio optimization is the backbone of quantitative finance and energy allocation.

Imagine we have a budget  $B$  (dollars). We can purchase  $n$  different assets (e.g. stocks, bonds) with current prices  $p$  (dollars per unit), expected returns  $\mu$  (dollars per unit), and covariance  $\Sigma$  (dollars squared per unit squared). Your goal is to ensure the standard deviation of your portfolio to be less than  $S$  (dollars). We are only buying assets, not borrowing them, so we cannot “short” stocks and have a “long”-only portfolio. Lastly, we don’t want to end up over-invested in a single asset, so, let’s ensure we never put more than 5% of our budget into a single asset.

Using the data in the notebook, <https://marimo.io/p/@cvxpy/port-opt>, find the portfolio that maximizes expected returns.

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**Rest of the homework is online!**